# **Coded Interleaving for Burst Error Correction**

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The concept of code interleaving has proved to be a very useful technique for dealing with complicated communications channels. One of the most recent applications of this concept is the Golay-Viterbi concatenation scheme proposed for use on the Mariner Jupiter/Saturn 1977 Mission. In this paper a generalization of interleaving is introduced. When two or more codes are suitably combined using this idea, the decoding algorithm for the first code can supply information about the location of errors for the remaining codes, thereby reducing the redundancy requirements for these codes.

### I. Introduction

The concept of code interleaving has proved to be a very useful technique for dealing with complicated communications channels. One of the most recent applications of this concept is the Golay-Viterbi concatenation scheme proposed for use on Mariner Jupiter/Saturn 1977 (Ref. 1). In this paper a generalization of interleaving is introduced. When two or more codes are suitably combined using this idea, the decoding algorithm for the first code can supply information about the location of errors for the remaining codes, thereby reducing the redundancy requirements for these codes.

We begin with a somewhat abstract definition of interleaved codes. Let  $C_i$  be a block code of length  $N_i$  over an alphabet  $V_i$ , a vector space of dimension  $k_i$  over GF(p). Let

$$V = \sum_{i=1}^{M} \bigoplus V_i$$

the direct sum space whose elements are represented by M-tuples  $(v_1, \dots, v_m)$  where  $v_i \in V_i$ . V has dimension  $k = \sum k_i$  over GF(p).

If  $\{c_i(t)\}$  is the sequence of symbols formed by encoding a sequence of symbols from source  $S_i$  using code  $C_i$ , then the *interleaved code* is the block code of length  $N = LCM(N_1, \dots, N_M)$  whose code words are of the form

$$\{c(t)\}_{1}^{N} = \{(c_{1}(t), \cdots, c_{m}(t))\}_{1}^{N}$$

The code is *interleaved to depth M*.

When the size of the symbol alphabet of a code C is different from the size of the channel alphabet, coding of the alphabet is necessary. When the channel has p symbols and the code alphabet is a k-dimensional vector space over GF(p), the coding can be achieved by selecting a basis for the vector space and transmitting the k coefficients  $(a_1, \dots, a_k)$  of a vector relative to the basis. The resulting sequence of kN terms from GF(p) will be called the channel code representing C. For example, if  $V_1, \dots, V_m$  are 1-dimensional in the above definition of interleaved codes and the basis for V is

$$\{(1,0,\cdots,0),(0,1,0,\cdots,0),\cdots,(0,\cdots,0,1)\}$$

then the channel code representing C is the usual definition of interleaved codes. That is, the subsequence  $\{a(j), a(j+k), a(j+2k) \cdots \}$  is just a sequence obtained from the jth code used in the interleaving. In general, let  $U_1, \cdots, U_k$  be a basis for V and

$$c(t) = \sum_{i=1}^{k} a_i(t) U_i$$

where  $(c(1), \dots, c(N))$  is a codeword in C. The set of kN-tuples  $\{(a_1(1), \dots, a_k(1), a_1(2), \dots, a_k(N))\}$  is the coded interleaved code formed from  $\{C_1, \dots, C_M\}$ .

## II. Analysis

The question arises as to the choice of basis for V. This depends on the channel error statistics and the mode of decoding.

Let  $P_i$  be the projection of V onto  $V_i$ ; that is

$$P_i(v_1, \cdots, v_m) = v_i$$

and let  $u_1, \dots, u_k$  be a basis for V. Then the mapping

$$(a_1, \cdots, a_k) \xrightarrow{L_i} \sum_j a_j P_i u_j$$

is a linear mapping from the set of k-tuples to  $V_i$  and the M-tuple  $(L_1, \dots, L_m)$  is the inverse of the coded interleaving mapping. If the component codes are to be decoded independently from a received sequence  $\{r_i(t)\}$ , then clearly the sequence  $v_j(t) = L_j(r_1(t), \dots, r_k(t))$  should be the input to the decoder for the jth code. The criterion for the choice of basis should be to minimize the error rate in as many component codes as possible. This choice depends on channel statistics. For example, let  $(a_1(t), \dots, a_k(t))$  and  $(\bar{a}_1(t), \dots, \bar{a}_k(t))$  be the only possibilities for  $(r_1(t), \dots, r_k(t))$ , where bar denotes

complementation. Then the basis should be chosen so that  $L_j(1, \dots, 1) = 0$  for all but one choice of j. M-1 codes would then be error free.

Another channel extreme occurs when

In this case, if an error occurs, it causes errors in each component code with high probability. Thus, if the decoding algorithm for one code detects an error in a given symbol, the corresponding forms in the other codes might just as well be erased and their decoding algorithm attempt to correct erasures.

The above example suggests that the following strategy may be useful for a large class of channels: use code  $C_1$  as an error correcting code. If it is decided that symbol  $c_1(t)$  is in error, erase  $c_j(t)$  for  $j = 2, \dots, M$ . Decode  $C_2, \dots, C_m$  as erasure channels.

It may happen that errors occur which do not affect  $C_1$  and, therefore, are not erased in  $C_2$ ,  $\cdots$ ,  $C_M$ . The following theorem is useful in this context.

**THEOREM.** Let the probability of error in a channel have the property

Prob 
$$[(r_1 \cdot \cdot \cdot r_k) = (a_1 \cdot \cdot \cdot a_k) + (e_1 \cdot \cdot \cdot e_k)]$$
  
=  $P(e_1 \cdot \cdot \cdot e_k)$ 

For each  $k_1 < k$  there exists a linear transformation  $L_1$  from k-tuples onto  $V^{k_1}(p)$  for which

$$egin{aligned} P_{L_1} &= \operatorname{Prob}\left[L_1\left(e_1, \ \cdots \ e_k
ight) 
ight. \ &= \mathbf{0}\left[\left(e_1 \ \cdots \ e_k
ight) 
eq \left(0, \ \cdots \ , 0
ight)
ight] 
otin rac{1}{p_{k_1}} \end{aligned}$$

*Proof:* Let 
$$\delta\left(\mathbf{0}\right)=1$$
 and  $\delta\left(v\right)=0$  for  $0\neq v\,\epsilon\,V^{k_1}(p)$ 

$$egin{aligned} P &= \operatorname{Prob}\left[L_{\scriptscriptstyle 1}\left(e_{\scriptscriptstyle 1}, \; \cdots, e_{\scriptscriptstyle k}
ight) = \mathbf{0} \, | \, (e_{\scriptscriptstyle 1}, \; \cdots, e_{\scriptscriptstyle k}) \ &
eq (0, \; \cdots, 0) 
brace \end{aligned}$$

$$=rac{1}{1-P\left(0,\cdots,0
ight)}ullet_{\left(e_{1},\cdots e_{k}
ight)
eq0}\sum_{\left(e_{1},\cdots e_{k}
ight)
eq0}P\left(e_{1}\cdot\cdot\cdot e_{k}
ight) 
onumber \ \delta\left(L_{1}\left(e_{1},\cdots,e_{k}
ight)
ight)$$

If we choose a basis for  $V^{k_1}$  and for the space of k-tuples,  $L_1$  is represented by a  $k_1$  by k matrix whose  $k_1$  rows are linearly independent. There are

$$(p^k-1)(p^k-p)\cdots(p^k-p^{k_1-1})$$

such matrices. We average the above equation over all such linear mappings.

$$egin{aligned} &\prod_{j=0}^{k_1-1} (p^k-p^j)^{-1} \sum_{L_1} P_{L_1} = \ &rac{1}{1-P\left(0,\,\cdots,\,0
ight)} \cdot \sum_{(e_1,\,\cdots\,e_k)\,
otag 0} P\left(e_1,\,\cdots,\,e_k
ight) \ & imes \sum_{L_1} \prod_{j=0}^{k_1-1} \left(p^k-p^j\right)^{-1} \delta\left(L_1\left(e_1,\,\cdots,e_k
ight)
ight) \end{aligned}$$

The innermost sum is nonzero only if  $L_1(e_1, \dots, e_k) = 0$ . If we choose as our basis for k-tuples one such that  $(e_1, \dots, e_k)$  is the first basis vector then  $L_1$  with  $L_1(e) = 0$  is described by a  $k_1$  by k matrix whose first column is zero and whose rows are linearly independent. The number of such is

$$\prod_{j=0}^{k_1-1} (p^{k_{-1}}-p^j)$$

The above equation then reduces to

$$\begin{aligned} \mathbf{Ave}\left(P_{L_{1}}\right) &= \frac{1 - P\left(0, \cdots, 0\right)}{1 - P\left(0, \cdots, 0\right)} \cdot \frac{\prod\limits_{j=0}^{k_{1}-1} \left(p^{k-1} - p^{j}\right)}{\prod\limits_{j=0}^{k-1} \left(p^{k} - p^{j}\right)} \\ &= \frac{1}{p^{k_{1}}} \cdot \frac{p^{k} - p^{k_{1}}}{p^{k} - 1} \leq \frac{1}{p^{k_{1}}} \end{aligned}$$

Since the average of  $P_{L_1}$  is less than or equal to  $1/p^{k_1}$ , there exists an  $L_1$  such that  $P_{L_1} \leq 1/p^{k_1}$ .

Q.E.D.

The theorem can be applied to the above decoding strategy as follows: If  $P_E$  is the probability of a k-tuple error in the channel and  $C_1$  is capable of correctly decoding all errors "seen" by it. Then the other component codes will have an erasure rate of  $P_E$  and an additional error rate of  $P_E \cdot 1/p^{k_1}$ . For reasonable values of  $k_1$  the other codes need be capable of finding few errors in addition to the erasures.

A variant of the above is that the extra errors found by  $C_2$  be used to insert extra erasures in  $C_3$ , etc. The design problem is not of finding the best  $L_1$  then the best  $L_2$ , etc., but finding the best sequence  $(L_1, L_2, \dots, L_M)$ .

### III. Conclusion

The concept of coded interleaving provides a richer class of codes than simple interleaving. It provides the ability to match the interleaving process to the channel statistics, thus allowing lower redundancy codes.

## Reference

1. Baumert, L. D., and McEliece, R. J., "A Golay-Viterbi Concatenation Scheme," in this issue.